

## **Motorized Potentiometer**

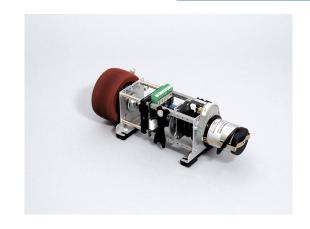
MR266 Remote Controlled Rheostats (20W - 600W)

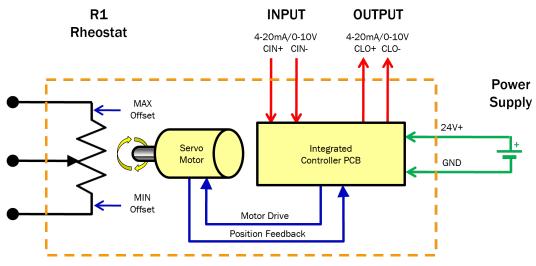


**MR266 SERIES** 

The MR266 series is a direct automation replacement for existing manual rheostat controls. Interface options include 4-20mA or 0-10V which ensures compatibility with the majority of PLC or DCS control systems

MR266 series replace a manually controlled, high power rheostat (20 watts up to 600 Watts). For low wattage potentiometer applications (< 5W), please refer to MR267 series data sheet.



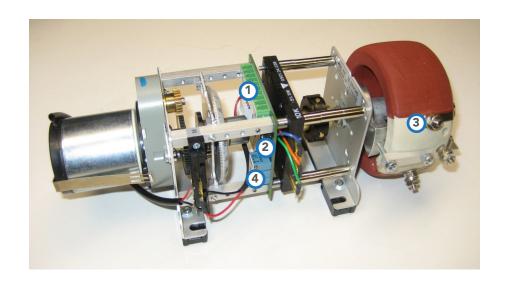


#### **Features**

- 35mm DIN Rail Mount
- 4-20mA or 0-10V input control
- Potentiometer Power Ratings from 20W to 600W
- Potentiometer Resistances from  $2\Omega$  to  $200k\Omega$
- User-Adjustable Timing Cycle from 10 to 120 Seconds

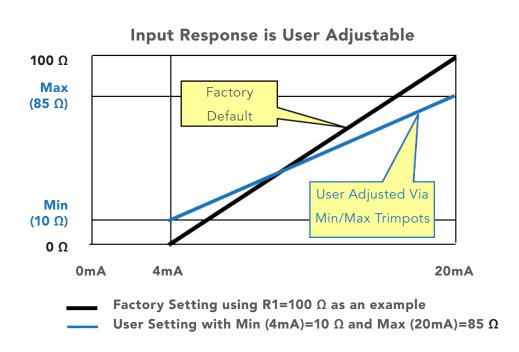




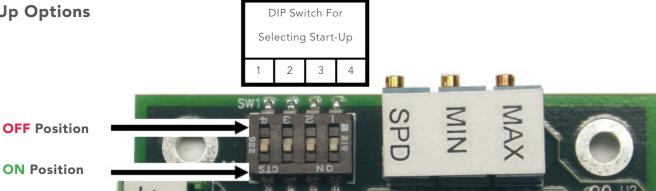


### Setting up the Motorized Rheostat

- Make Power, Input, and Output Connections to Controller using the supplied PHOENIX plug.
   Note: if using MR267A Accessory, first mount to front panel and then connect to special mating receptacle on bottom side of Controller PCB (not visible in this photo).
- 2. Set DIP switches for desired Override and Bias modes. See following page for detailed explanation of settings and factory defaults.
- 3. Make connections to Rheostat. Crimp-style ring or blade terminals are recommended
  - For 20W/60W models, use size #4 or M3
  - For 170W/300W/600W models, use size #8 or M4
- 4. Adjust Min and Max offset if 4mA/0V and/or 20mA/10V set points are to be different than default  $0\Omega$  and Full Scale settings, respectively. Adjust SPD trimpot for timing cycle other than the default setting of 10 seconds (Adjustable range is 10-120 seconds).



## **Start-Up Options**

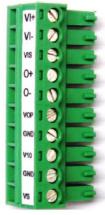


DIP SW	Function	Description 4	-20mA	0-10V
Position			Defa	ult Default
1	Input Bias	ON = Input range is 4-20mA or 2-10V. OFF = Input range is 0-20mA or 0-10V.	ON	OFF
2	Output Bias	ON = Output range is 4-20mA or 2-10V.  OFF = Output range is 0-20mA or 0-10V.	ON	OFF
3	Override Mode	ON = Manual override disengages motor contruntil a Reset is performed. Optional MR267A ac sory provides a turnkey remote Reset pushbutto indicator solution.  OFF = Manual override is disabled. System will motor to position determined by analong output	cces- on/ drive	ON
4		Not used	ON	ON

## **Controller Connections**

PIN	Function	Description
1	I+ or V+	Input Signal Positive. May be either current (I+) or voltage (V+) depending on configuration.
2	I- or V-	Input Signal Return (Negative). May be either current (I-) or voltage (V-) depending on configuration.
3	VIS	Isolated voltage available for customer use. Voltage is nominal 12V. Maximum load 30mA. Can be used to power an external 4-20mA loop power sensor. Available on isolated 4-20mA Input Option 2 only.
4	0+	Position output. May be either curent or voltage depending on option
5	0-	Position output return signal. May be either curent or voltage depending on option.
6	VOP	Isolated voltage available for customer use. Voltage is nominal 12V. Maximum load 30mA. This isolated voltage is only available with isolated 0-10V Input/Output.
7	GND	System ground. Internally connected to pin 9.
8	V10	Precision Reference output 10V. Maximum load 6mA. May be used to power remote control potentiometer. Voltage is referenced to system ground. Optional HPF00-7-0-0 Remote Potentiometer accessory is available as a turnkey solution.
9	GND	System ground. Internally connected to pin 7.
10	24+	System power. Connect to external power supply. Peak current draw when motor is running is 220mA. Typical idle current draw is <60mA.





## I/O Option 22

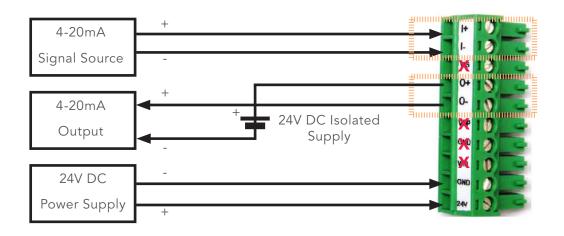
Input = Isolated 4-20mA



Output = Isolated 4-20mA, Loop Powered

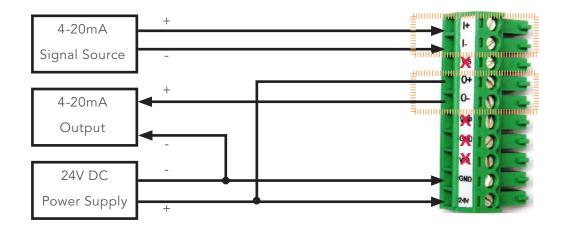
## Isolated Input/Output Using

#### External 24V DC isolated Power Supply



#### Isolated Input/Output Using

#### External 24V DC isolated Power Supply

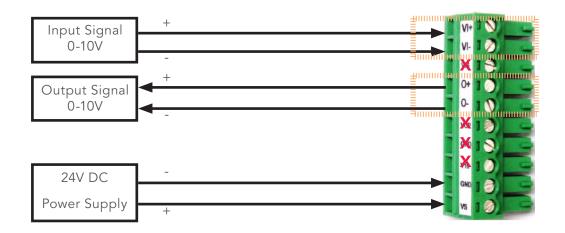


## I/O Option 44

Input = Isolated 0-10V

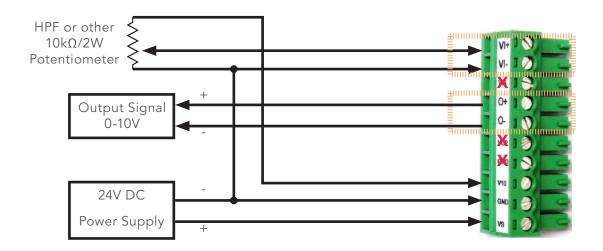
Output = Isolated 0-10V





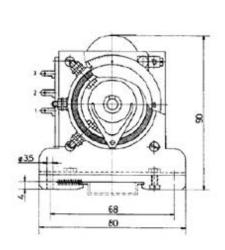
#### **Connections for Remote Potentiometer**

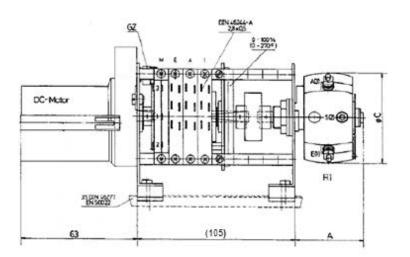
Used to Control Local MR267 Motorized Potentiometer



## **Reference Drawings**

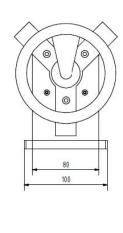
20-60-170 Watt Models

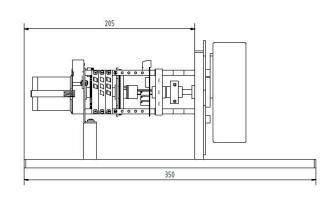


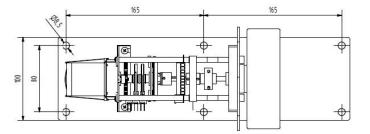


Power	Α	ØС
Rating	(mm)	(mm)
20 W	32	35
60 W	42	50
170 W	66	80

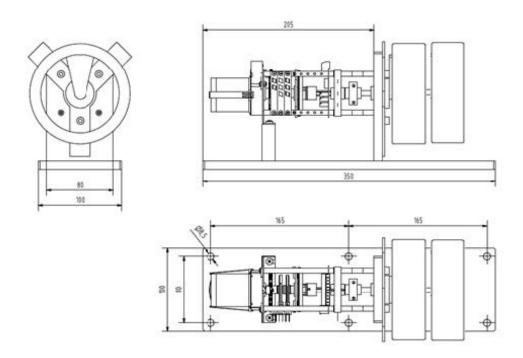
300 Watt Model







## 600 Watt Models



# **Specifications**

-		
Analog Input		
Position Input Current Input Bias = ON	-4mA to 20mA	A signal dropout below 4mA will cause the motor pot to remain at its last position. Signals ≥20mA are interpreted as 20mA signal.
Input Bias = Off	0mA to 20mA	Signals $\leq 0$ mA or less are interpreted as 0 position. Signals $\geq 20$ mA are interpreted as 20mA signal.
Position Input Voltage Input Bias = ON Input Bias = OFF	2V to 10V 0V to 10V	Signals ≤2V are interpreted as 0 position. Signals ≥10V are interpreted as 10V signal.  Signals ≤0V are interpreted as 0 position. Signals ≥10V are interpreted as 10V signal.
Input Isolation	1kV	Only applies if isolated input option is ordered
Reference Output	10.00V, max 6mA	Used to power external potentiometer. Voltage referenced to system ground.
Position Accuracy	0.5% m	
Position Resolution	0.25% typical	
TIME Setting Range	10s to 120s	Default factory setting is 10 seconds.
MIN Setting Range	0% to 25%	Corresponds to 4mA / 0V input. Default setting is 0%
Max Setting Range	52% to 100%	Corresponds to 0mA / 10V input. Default setting is 100%

Description	Potentiometer Output		
Linearity  2% over electrical angular range  2% over electrical angular range  Angular range  Power Rating  DPM20  DPM20  DPM20  DPM300  DPM400  DPM300  DPM400  DPM400  DPM400  DPM300  DPM400  DPM4000  DPM400	Туре	Wire Wound	See DPC data sheet for additional technical details
Linearity    2% over electrical angular range	Resistance Tolerance	±5%	
DPM20 DPM60 DPM60 DPM60 DPM300 DPM300 DPM600 300W at 40°C DPM600 Dielectric Strength  Delectric Strength	Linearity		Rheostats have mechanical versus angular range. The difference is due to the wide wiper landing pad at the upper and lower ends. The default factory setting will place the Min and Max points in the center of the landing pads. The user can readjust the Min and Max points as needed.
Analog Output  Position Output Current Power Supply Loop Voltage Output Bias = ON Output Bias = OFF  Position Output Voltage Load Current Output Bias = ON Output Bias = OFF  Position Output Voltage Load Current Output Bias = OFF Ov to 10V Output Bias = OFF Ov to 10V Output Isolation  IkV Only applies if isolated output option is ordered  Position Accuracy O.5% max Position Resolution  Power  Supply Voltage Supply Voltage Supply Voltage Supply Current Standby Running Peak Suman Su	DPM20 DPM60 DPM170 DPM300	60 W at 40°C 170W at 40°C 300W at 40°C	
Position Output Current Power Supply Loop Powered Output Bias = ON Output Bias = OFF Omato 20mA Output Bias = OFF Output Bias = OFF Output Bias = OFF Output Bias = OFF Over Supply Output Bias = OFF Over Supply Output Solation Output Bias = OFF Over Supply Output Solation Standby Position Resolution Standby Position Resolution Standby Peak Supply Output Solation Peak Supply Output Solation Standby Peak Supply Output Solation Peak Supply Output So	Dielectric Strength	2000V AC, 50 Hz, 1 min	
Power Supply Loop Powered Loop Voltage Output Bias = OFF Output Bi	Analog Output		
Load Current Output Bias = ON Output Bias = OFF Output Isolation Output Is	Power Supply Loop Voltage Output Bias = ON	26V max 4mA to 20mA	$500\Omega$ external burden resistance, max with 24 V or higher
Position Accuracy Position Resolution  Power  Supply Voltage  Supply Current Standby Running Peak Soum Amax  Standby Peak Soum Amax  Standby Peak Soum Amax  Standby Peak Soum Amax  Standby Peak Soum Amax  Soum	Load Current Output Bias = ON	2V to 10V	
Position Resolution  Power  Supply Voltage  Supply Current Standby Running Peak Sund Standby Peak Supply Current Standby Running Peak Sund Standby Peak Supply Current Standby Running Peak Sund Standby Sund Stant and stop peaks may reach the peak maximum. Recommended power supply is 24VDC at 400mA  Environmental  Temperature Operating Storage Storage -15°C to +65°C -25°C to +75°C  Humidity O-95% non condensing  Physical Attributes  Weight 20W 23 oz (630g) 60W 26 oz (730g) 170W 36 oz (1020g) 300W 43 oz (1220g)	Output Isolation	1kV	Only applies if isolated output option is ordered
Power  Supply Voltage 20V to 26V DC  Supply Current	Position Accuracy	0.5% max	
Supply Voltage  Supply Current Standby Running Peak  Environmental  Temperature Operating Storage Physical Attributes  Weight 20W 23 oz (630g) 60W 170W 300W  When the motor has reached position, the current consumption is reduced to a standby current. During a typical move, the current draw is approximately 200mA. Start and stop peaks may reach the peak maximum. Recommended power supply is 24VDC at 400mA  Environmental  -15°C to +65°C -25°C to +75°C  Humidity 0-95% non condensing  Physical Attributes  Weight 20W 23 oz (630g) 60W 26 oz (730g) 310W 3300W 43 oz (1220g)	Position Resolution	0.25% typical	
Supply Current Standby Running Peak SomA ypical SomA ypical Peak SomA ypical yournent. During a typical move, the current draw is approximately 200mA. Start and stop peaks may reach the peak maximum. Recommended power supply is 24VDC at 400mA  Environmental  Temperature Operating Storage Stora	Power		
Standby Running Peak Peak Stommental  Temperature Operating Storage Physical Attributes  Weight 20W 60W 60W 60W 60W 710W 710W 710W 710W 710W 710W 710W 71	Supply Voltage	20V to 26V DC	
Temperature Operating	Standby Running	200mA typical	When the motor has reached position, the current consumption is reduced to a standby current. During a typical move, the current draw is approximately 200mA. Start and stop peaks may reach the peak maximum. Recommended power supply is 24VDC at 400mA
Operating	Environmental		
Weight  20W  23 oz (630g)  60W  26 oz (730g)  170W  36 oz (1020g)  300W  43 oz (1220g)	Operating Storage	-25°C to +75°C	
20W 23 oz (630g) 60W 26 oz (730g) 170W 36 oz (1020g) 300W 43 oz (1220g)	Physical Attributes		
	20W 60W 170W 300W	26 oz (730g) 36 oz (1020g) 43 oz (1220g)	Specifications subject to change without notice

Specifications subject to change without notice

#### **Ordering Info** MR266 Motorized Potentiometer MR266 Input/Output Interface 22 4-20mA, Isolated 44 0-10V, Isolated **Potentiometer Power Rating** Α DPM20 (20W) В DPM60 (60W) C DPM170 (170W) D DPM300 (300W) Ε DPM600 (600W - Dual DPM300 Pots) NOTE: Dual pots can be wired in series or parallel. Potentiometer Resistance NOTE: $2\Omega$ not available in DPM20 series. 2Ω 2 3Ω NOTE: $3\Omega$ not available in DPM20 series. 3 5Ω 4 10Ω 5 20Ω 25Ω 6 7 9 50Ω 8 100Ω 200Ω 10 250Ω 11 500kΩ $1k\Omega$ $2.5k\Omega$ 12 13 2kΩ 14 15 $5k\Omega$ $10k\Omega$ **17** $15k\Omega$ 16

NOTE:  $20k\Omega$  not available in DPM20 series.

NOTE:  $25k\Omega$  not available in DPM20 and DPM60 series.

NOTE:  $50k\Omega$  not available in DPM20 and DPM60 series.

NOTE:  $100k\Omega$  only available in DPM300 and DPM600 series.

NOTE:  $200k\Omega$  only available in DPM300 and DPM600 series.

## **Ordering Info**

 $20k\Omega$ 

 $25k\Omega$ 

 $50k\Omega$ 

 $100k\Omega$ 

 $200k\Omega$ 

18 19

20

21

22

1803659 Replacement Phoenix Mini Combicon Plug