

FIBER OPTIC INCREMENTAL ENCODER

MR320 Controller Module

MR320 SERIES

The MR320 Controller module is the active optical and electrical interface for the MR320 series ZapFREE® Fiber Optic Incremental Encoder System. The module incorporates multiple built-in interfaces for compatibility with PLCs, motor drives, and other motion control systems.



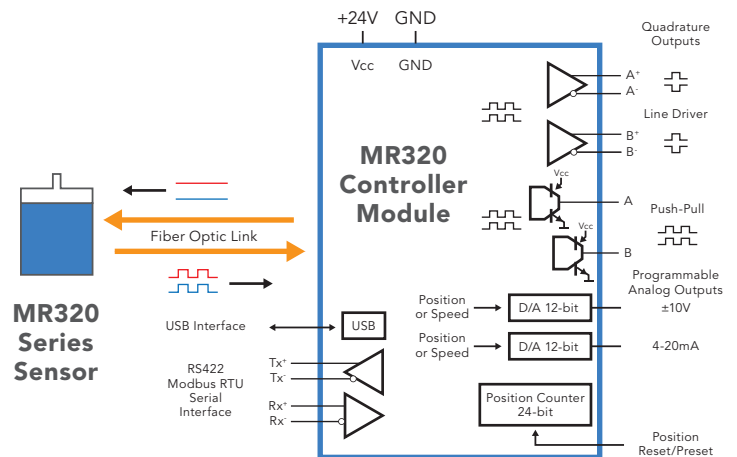
U.S. Patent 7,196,320
Inherently Safe Optical Radiation
For EPL Mb/Gb/Gc/Db/Dc

Features

- Mounts on standard 35mm DIN Rail
- Operates from +15VDC to +32 VDC power supply
- Inherently Safe Optical Radiation
- Controller is installed outside of hazardous area
- Interference-free transmission up to 2500 meters

Interfaces

- A/B quadrature outputs – line driver and push-pull
- Programmable 4-20mA output, Position or Speed
- Programmable ±10V output, Position or Speed
- USB interface
- RS485/Modbus RTU interface
- RS232 with optional MR232-1 adapter



System Planning

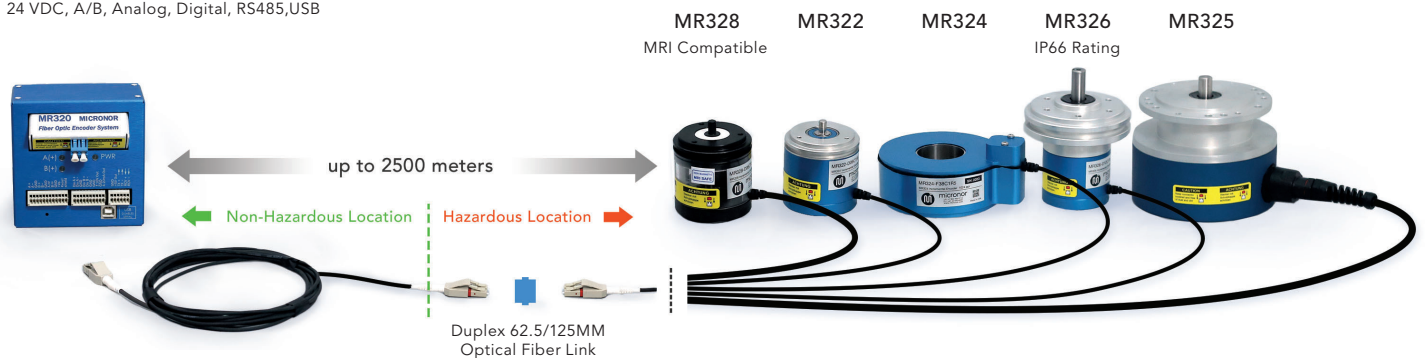
MR320 Controller

Inherently Safe Optical Radiation

24 VDC, A/B, Analog, Digital, RS485, USB

MR320 Series Sensor

Simple Mechanical Device



1. Verify cabling and junction boxes compatible with the operating environment.
2. Verify that the optical link loss is within the Controller's Maximum Loss Budget.
3. Consult Application Note AN118 for more information, examples and guidance on loss budget.

ZAPPY® Configuration Software

As delivered, the Micronor ZapFREE® Fiber Optic Encoder System (consisting of MR320 series fiber optic encoder and MR320 module) are pre-programmed, ready to be connected and operated using the Direct Quadrature outputs. However, many user applications intend to use the auxiliary functions and operating modes within the encoder firmware, including Quadrature Multiplier/Divider, Position Counter, Analog Outputs or to run Diagnostics. For these latter functions, the user needs to use the supplied ZAPPY® Configuration/Diagnostics program to perform a one-time setup for configuring these functions. The software is designed to run on a PC running under Windows XP or later. The PC can be connected to the MR320 module via built-in USB or RS422/RS485 interfaces. RS232 interface capability with optional MR232-1 RS485-to-RS232 Converter Cable. Typical ZAPPY® screens are shown below:

Encoder Parameters Set-Up Screen

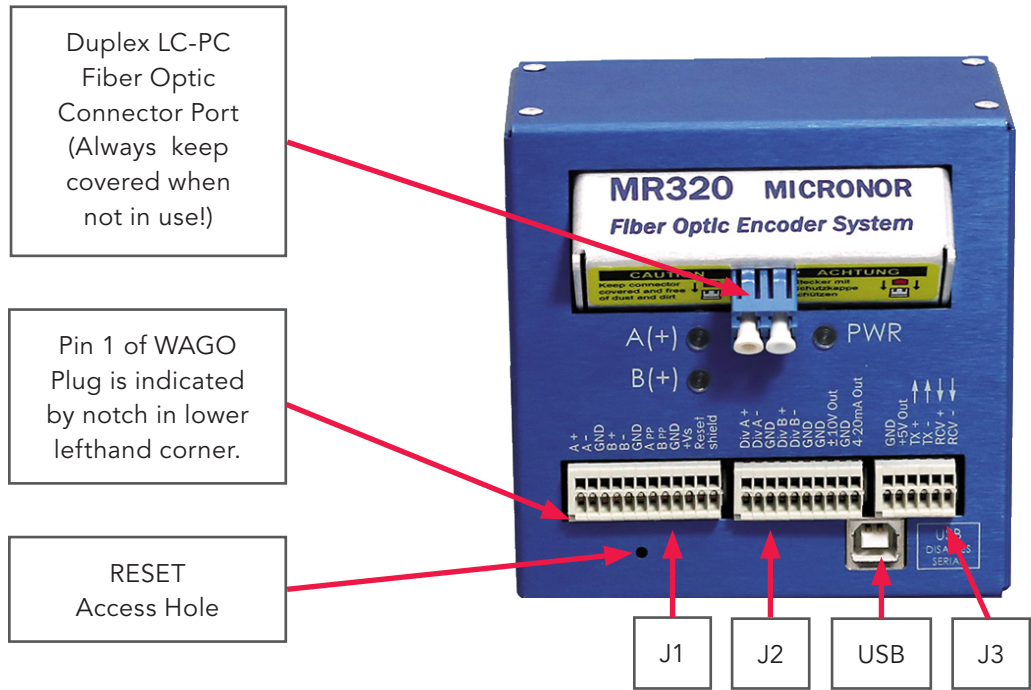
The screenshot shows the 'Encoder Parameters Set-Up Screen' of the ZAPPY Encoder Setup software. The window title is 'ZAPPY - Encoder Setup VER3.55 [© 2004 - 2014 by MICRONOR]'. The interface includes a menu bar with options: Home, Load Param, Save Param, Encoder, Upload to PC, Save to Unit, Operate, Diagnostics, Instructions, and EXIT. A 'Restore Default Values' button is located below the menu bar. The main area contains a table titled 'Edit the Parameter Values in the Column titled Value'.

Parameter Name	Register	Cmd Mode	Unit	Min.	Max.	Value	Default
Device Name	16	Read_Only	-	-1	-1		
Firmware Version	17	Read_Only	-	-1	-1		
Serial Number	18	Read_Only	-	0	10000000		
Address	12	Read_Write	byte	17	255		234
Resolution	10	Read_Write	counts	98	1024		180
Cal Interval	11	Read_Write	3s step	1	200		84
Duty Cycle Adjust	1A	Read_Write	-	0	128		105
Divider	21	Read_Write	counts	2	8192		3
Voltage Mode	23	Read_Write	-	0	2		0
Voltage Scale	24	Read_Write	RPM	10	8388607		1000
Voltage Filter	25	Read_Write	ms	1	128		32
Current Mode	26	Read_Write	-	0	6		0
Current Scale	27	Read_Write	RPM	10	8388607		0
Current Filter	28	Read_Write	ms	1	128		1
Pos. Reset Mode	29	Read_Write	-	0	1		0
Quad Multiplier	2A	Read_Write	-	0	1		0
Direction	2B	Read_Write	-	0	1		0
Hrdwr Reset Point	2C	Read_Write	counts	-8388607	8388607		0
Reset on Count	2D	Read_Write	counts	0	8388607		0

Real-Time Encoder Status Screen

The screenshot shows the 'Real-Time Encoder Status Screen' of the ZAPPY Encoder Setup software. The window title is 'ZAPPY - Encoder Setup VER3.55 [© 2004 - 2014 by MICRONOR]'. The interface includes a menu bar with options: Home, Load Param, Save Param, Encoder, Upload to PC, Save to Unit, Operate, Diagnostics, Instructions, and EXIT. The main area displays a 'Real Time' section with a circular speedometer showing 'RPM x100' at 70.33. To the right of the speedometer is a 'Meter Scale' input field set to 1000. Below the speedometer is a 'Position Counter' section showing a value of 1848, a 'Reset Counter' button, and a checked 'Display Counter' checkbox.

Electrical and Optical Connections



J1 Wago PN: 733-112 (12 Pin Terminal)	
1	A+ (5V)
2	A- (5V)
3	GND
4	B+ (5V)
5	B- (5V)
6	GND
7	A Push-Pull (24V)
8	B Push-Pull (24V)
9	GND
10	+Vs
11	Counter Reset
12	Shield

J2 Wago PN: 733-110 (10 Pin Terminal)	
1	Div A+ (5V)
2	Div A- (24V)
3	GND
4	Div B+ (5V)
5	Div B- (24V)
6	GND
7	GND
8	± 10V Out
9	GND
10	4-20mA

J3 Wago PN: 733-106 (6 Pin Terminal)	
1	GND
2	+5V Out
3	TX+ (Output)
4	TX- (Output)
5	RCV+ (Input)
6	RCV- (Input)

Specifications

Electrical Interfaces	
Direct Quadrature Outputs	
Bandwidth	70kHz max
Format	A/A'/B/B' RS422 (5V) Line Driver and A/B Push-Pull (24V)
POSITION COUNTER Range	Direction/Sign Bit plus 24-bit counter value ($\pm 8,388,607$, equivalent to 8,192 revolutions with MR324 1024ppr encoder). Both software and hardware Zero (calibration) Set available.
DIVIDER Quadrature Outputs	DIVIDER range is 2-8192, A/B RS422 Line Driver (5V) and A/B Push-Pull (24V) Outputs..
Analog Outputs	Each output is individually programmable for Position (full-scale range of 1-8,388,607 counts) or SPEED (full-scale range of 10-10,000 RPM)
Current Output:	Range: 0mA to 24mA, Max Burden Resistance: 500 Ω (24V supply)
Voltage Output:	Range: $\pm 12V$; Max Current: 5mA (2k Ω load); Short Circuit < 5 seconds
RS422/485 Interface	Direct connection via J3, Modbus RTU compatible
RS232 Interface	With optional MR232-1 Converter Cable
Modbus interface	Modbus (RTU) compatible RS422/RS485 interface
USB interface	USB built-in, disables RS485/Modbus interface when used
Electrical Connections	J1, J2, J3 connections via WAGO QuickConnect Plugs (supplied with MR320)
Optical Interface	
Optical Interface	LC Duplex, 62.5/125 μ m Graded Index Fiber, 0.275NA, Type OM1
System Loss Budget	12.5dB
Maximum Optical Link Length	Up to 2500 meters (8300 ft) with MR320 series Sensors Consult Application Note AN118 for more information. Contact Micronor for longer distance requirements.
Laser Safety	Class 1 per IEC 60825-1
Power Supply	
Power Supply Input	+15VDC to +32VDC, 60mA (During Power Up, power supply should be capable of delivering a momentary current in excess of 100mA.)
+5V Output	10mA maximum load. (Designed for powering MR232-1 RS485/RS232 adapter cable)
Explosive Atmospheres	
EX Classification	Controller shall be installed in non-hazardous location only Power supply to Controller shall be current limited to 200mA IECEX Test Report (ExTR) GB/CML/ExTR 16.0039/00
ATEX	EPL Mb/Gb/Gc/Db/Dc
IEC Ex	EPL Mb/Gb/Gc/Db/Dc
NEC	Exempt
Environmental Performance	
Temperature/Humidity	-5° to +55°C / 30% to 85% RH (non-condensing)
Ingress Protection	IP40
Physical Attributes	
Mounting	35mm DIN Rail
Housing Dimensions	102mm W x 102mm D x 68mm H
Weight	300g (10.5oz)

Specifications subject to change without notice

Ordering Info

MR320

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