

Fiber Optic Sensors are replacing their Electrical Counterparts in Critical Applications

Presented by Dennis Horwitz, President

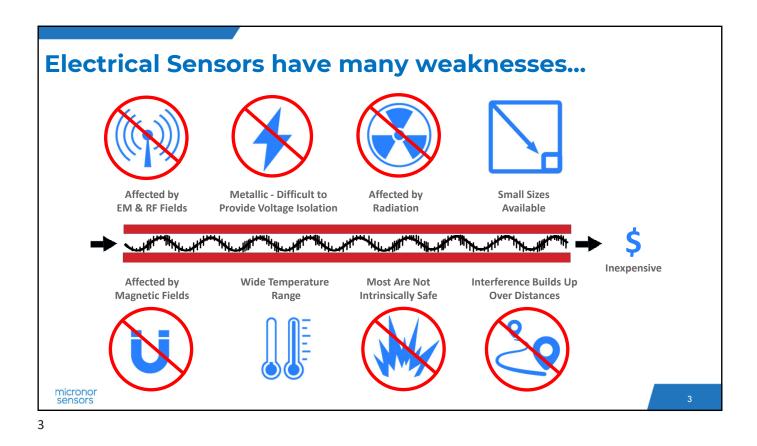
Sensors Converge LIVE Theater Wednesday, June 25 2025

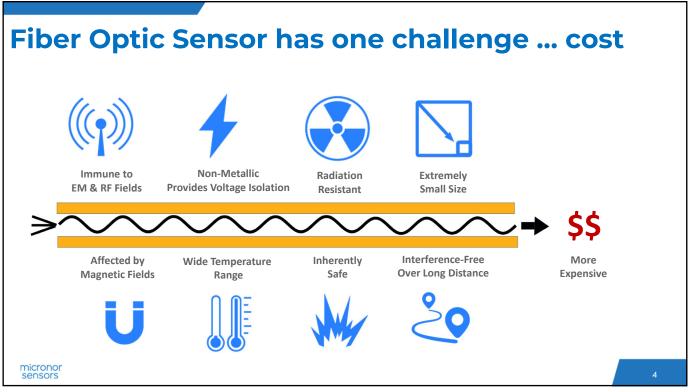
Today's Industrial Trends drive needs for Sensors of All Types

Trend	What/Why/Where	Issue
Electrification	Reduce use of fossil fuels, lower carbon footprint, combat climate change	Creates EMI/RFI Problems
Closed Loop Processing	Automation, robotics, process & equipment health feedback for increased efficiency and lower costs	Need for variety of sensors for better process monitoring, better yields, and predictive maintenance
Medical Devices	Surgical & biopsy robots, treatment delivery, MRI, patient rehabilitation	Need variety of sensors, low cost, small size, enhance health & longevity
Harsh Environments	Transformers, generators, oil & gas, pipelines, wind turbines, underwater, nuclear	Need very robust sensors – resistant to harsh environment factors
Hazardous Locations	Food industry, chemical, mines, food & process industries	Need for intrinsically safe or inherently safe sensors
Vehicle Health	Automotive, aerospace, rail transport	For increased safety and reliability
Structural Health	Buildings, dams, highways, railroad tracks, pipelines, transmission lines	For increased safety and reliability, eliminate waste caused by leakage

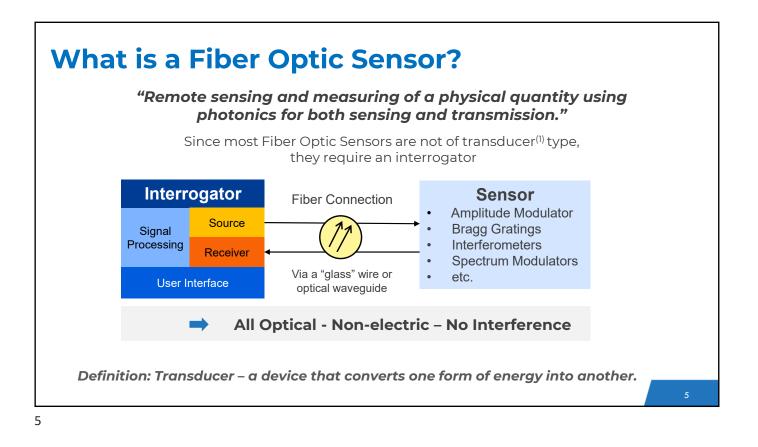
2

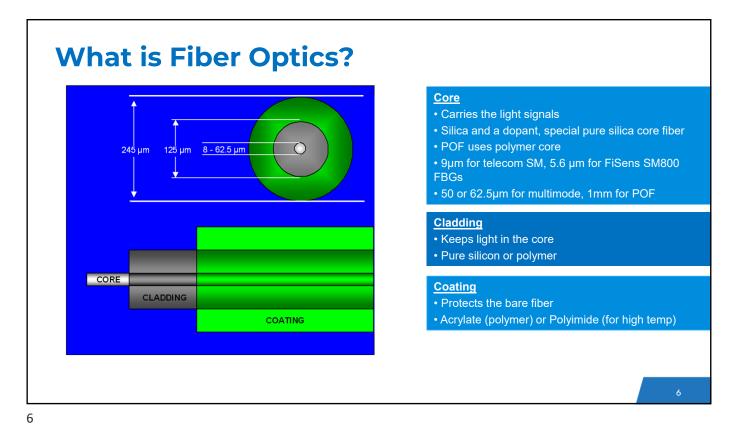
1

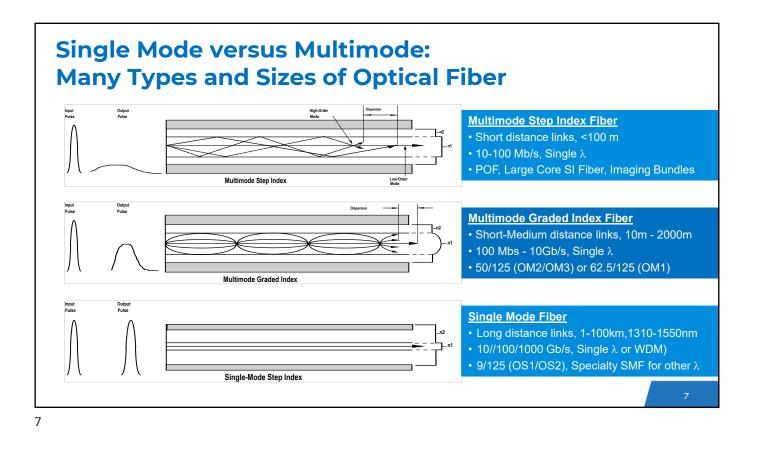


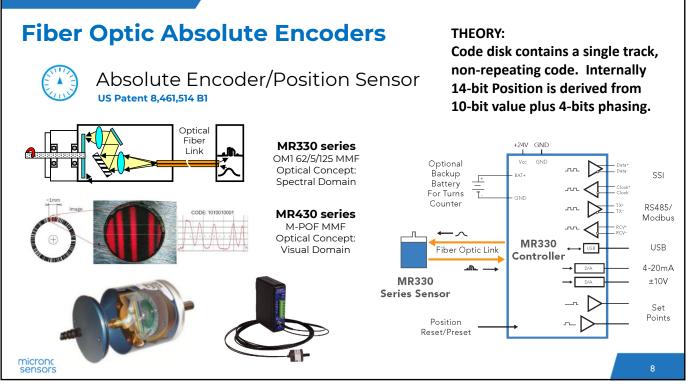


4

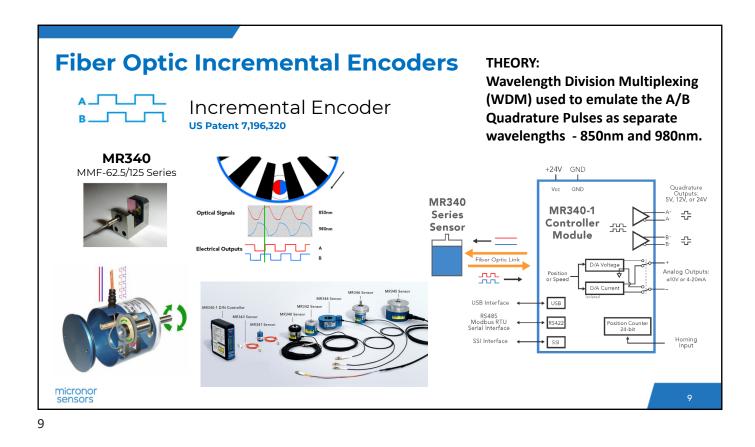




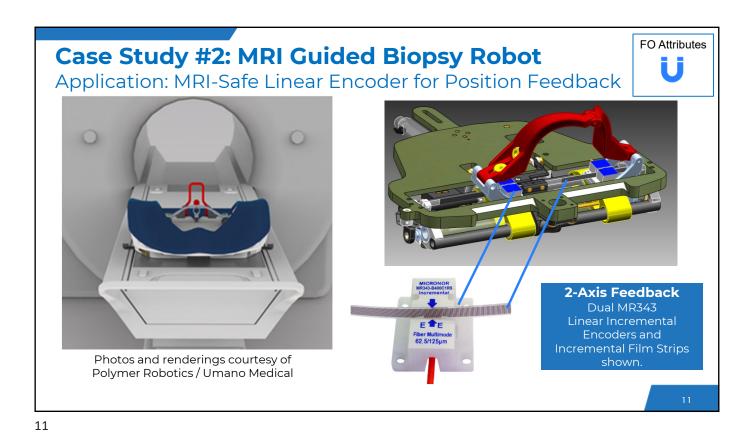


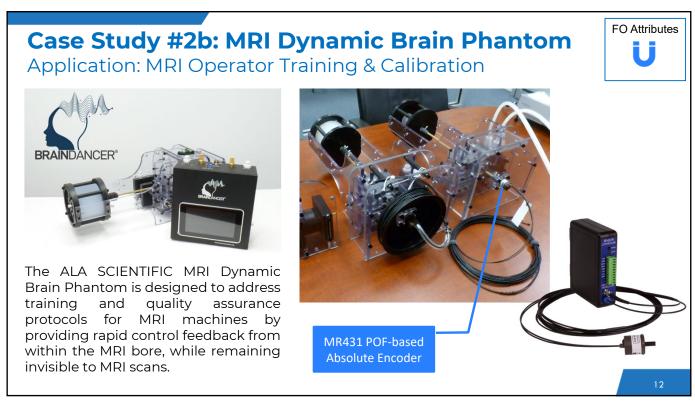


8









FO Attributes

Case Study #3: ITER Fusion for Energy Project Application: High Resolution FO Encoders for IVVS





APPLICATION

The mission of Fusion for Energy (F4E) is to make fusion possible on Earth. ITER ("The Way") will be the first fusion device to generate more heat than is used to start the reaction. The process involves raising the temperature to 150 million °C to generate super-hot plasma, producing 500 MW of heat for about 7 minutes.

CHALLENGE

When the fusion device is turned off, the In-Vessel Viewing System (IVVS) needs to examine plasma-facing components in the vacuum vessel. This requires an extremely precise inspection system.

SOLUTION

Six probes are used at different points within the machine. Each uses a laser beam and rotating turret to scan the surface, producing a 3D map of the machine. Extremely high-resolution FO Encoders were developed by Micronor AG for IVVS.

13

13

MR380 Series Fiber Optic Emergency Stop and Microswitch Operate on basic principle of photo interruption +24V GND (light on / light off) <u>t</u> MR386 MR380 **Nicroswitch** Controlle Fiber Optic Lin MR387 E-STOP Sensor FO E-Stop available for use with SM, MM & POF Multiple FO E-Stops can be connected in linear or loop topologies, depending on application needs Controllers can be used to extend distance of existing EM E-Stops Distances up to 18 km micronor sensors





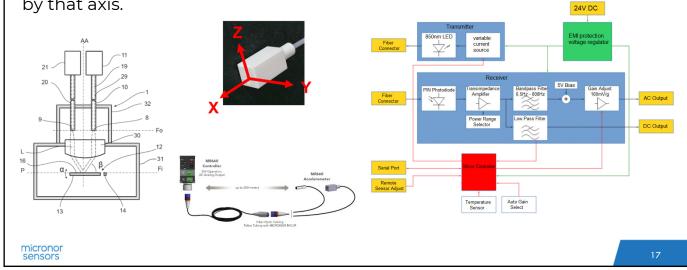
15



16

MR660 Multi-Axis Fiber Optic Acceleration/Vibration Sensor

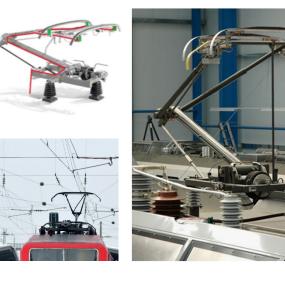
A dedicated MEMS membrane/mirror is aligned with a specific axis and light is modulated only by that axis.



17

Case Study #6: Electric Train Pantograph Application: Pantograph & Catenary Vibration Anomalies





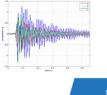
CHALLENGE

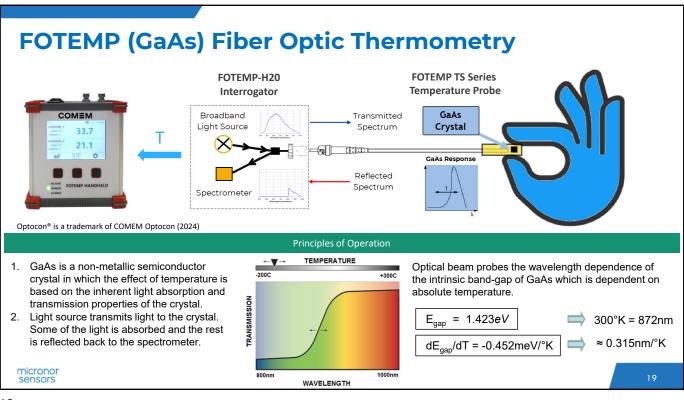
Dynamically monitor pantograph operation in real time during train operation. A serious failure of pantograph can not only damage contact wires but can also inflict widespread damage on the catenary system network.

SOLUTION

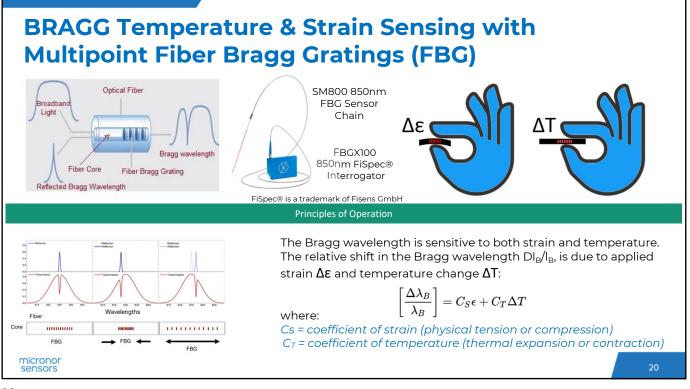
Providing high voltage immunity and isolation, a multi-axis fiber optic accelerometer mounts directly on the pantograph to monitor system health in real time. Data is also used to monitor the health of the catenary system.

Customer: Swiss Railway





19



20

FO Attributes

Case Study #7: Induction Heating

Application: Measuring Temperature in RF Field





CHALLENGE

Magnetic nanoparticles are heated with induction to selectively ablate tumor cells, powers from 1kW to 10kW, frequencies from 150kHz to 400 kHz. This non-contact selective heating only elevates the temperature of the material or tissue with **embedded magnetic nanoparticles**. Requires RF immune temperature sensor to monitor actual temperature.

SOLUTION

Ambrell EASYHEAT® System is a compact induction heating system for the lab which offers COMEM Optocon's FOTEMP GaAs-based TS3 FO Temperature Probe (both non-metallic and RF-immune) for both temperature monitoring and control. Recently, customers have started to use Multipoint BRAGG FBGbased Temperature Probes for measuring gradients.

FOTEMP TS3 Probe

Multipoint BRAGG Probe

21

Case Study #8: Microwave Oven & Reactors Application: Measuring Temperature in MW Oven





CHALLENGE

Develop optimized process for meat thawing as well as production of partially cooked food product.

SOLUTION

A&B Famous Gefilte Fish uses the 4-Channel Bench Top FOTEMP signal conditioner together with FOTEMP TS3 series temperature probes.

A&B developed a proprietary microwave ovenbased process for raw fish thawing as well as production of their partially cooked frozen gefilte fish product. For the latter, a microwave oven process was developed that precisely cooks and cools the product without rendering the proteins fully cooked.

FOTEMP

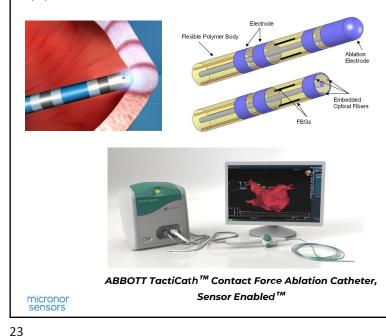
TS3 Probe

22

FO Attributes

Case Study #9: Medical – RF Ablation

Application: Contact Force of Ablation Catheter



CHALLENGE

RF ablation catheter is directed through the body and positioned to burn off tumors. Physicians require real-time, objective measure of contact force during treatment of cardiac arrhythmias or tumors.

SOLUTION

The TactiCath force-sensing ablation catheter provides physicians with a real-time, objective measure of contact force during the treatment of cardiac arrhythmias. It includes a smaller fiber optic sensor at the tip, a force-time integral display and automatically generated summary reports of the procedure. Contact force is derived from three sensor fibers which measure micro deformation of the catheter tip using Fiber Bragg Grating technology.

Case Study #10: Robotic Touch Force Sensing Application: Force of Loads, Gripping and Grasping





APPLICATION

Closed-loop robotic touch and force feedback in Harsh Environments characterized by electromagnetic fields and interference.

CHALLENGE

Conventional strain gauge sensors are susceptible to errors and interferences:

- Changes in resistance due to temp and humidity
- Hysteresis, creep, or fatigue that reduce accuracy and repeatability
- Require Calibration, compensation or correction for differing loading conditions.



FBG-based Load Cells, Gripper and Grasper force sensors provide electromagnetic immunity, high precision, accuracy, and reliability.

