

**Compact** magnetic

ESAV361 / ENAV361 (shaft / hollow shaft)

**Analog** 



The ESAV361(shaft) and ENAV361 (hollow shaft) singleturn encoders with analog interface and magnetic sensor technology are particularly flexible in use due to their diverse interfaces and measuring ranges.

A green LED as reference point and a red LED as error indicator simplify both installation and error diagnosis.





capacity



















resistant protection

salt spray tested

Reliable and insensitive

- Sturdy bearing construction in Safety-Lock™ design for resistance against vibration and installation errors.
- · Reduced number of components ensures magnetic insensitivity.
- IP67 protection and wide temperature range -40 °C ... +85 °C.

#### **Application oriented**

- · Current output 4 ... 20 mA.
- Voltage output 0 ... 10 V or 0 ... 5 V.
- · Different measuring ranges.
- Set input for easy start-up.

Order code **Shaft version**  ESAV361 |X|X|X|X|.|X|X|X|2000000

If for each parameter of an encoder the underlined preferred option is selected, then the delivery time will be 10 working days for a maximum of 10 pieces. Qts. up to 50 pcs. of these types generally have a delivery time of 15 working days.



a Flange

1 = clamping flange, IP67, Ø 36 mm [1.42"]

3 = clamping flange, IP65, ø 36 mm [1.42"]

2 = synchro flange, IP67, ø 36 mm [1.42"]

4 = synchro flange, IP65, ø 36 mm [1.42"]

**b** Shaft (ø x L), with flat

 $1 = \emptyset 6 \times 12.5 \text{ mm} [0.24 \times 0.49"]$ 

 $3 = \emptyset 8 \times 15 \text{ mm} [0.32 \times 0.59"]$ 

 $5 = \emptyset 10 \times 20 \text{ mm} [0.39 \times 0.79"]$ 

 $2 = \emptyset 1/4" \times 12.5 \text{ mm } [0.49"]$ 

Output circuit 1)

3 = current output 4 = voltage output Type of connection

1 = axial cable, 1 m [3.28'] PVC

A = axial cable, special length PVC \*)

 $2 = radial \ cable, 1 \ m \ [3.28'] \ PVC$ 

B = radial cable, special length PVC \*)

3 = axial M12 connector, 5-pin

4 = radial M12 connector, 5-pin

\*) Available special lengths (connection types A, B): 2, 3, 5, 8, 10, 15 m [5.56, 9.84, 16.40, 26.25, 32.80, 49.21'] order code expansion .XXXX = length in dm ex.: 8.M3651A.433A.3112.0030 (for cable length 3 m)

• Interface / resolution / supply voltage 3 = 4 ... 20 mA / 12 bit / 10 ... 30 V DC

4 = 0 ... 10 V / 12 bit / 15 ... 30 V DC  $5 = 0 \dots 5 \text{ V} / 11 \text{ bit} / 10 \dots 30 \text{ V DC}$ 

Measuring range

 $1 = 1 \times 360^{\circ}$ 

 $2 = 1 \times 180^{\circ}$ 

 $3 = 1 \times 90^{\circ}$ 

 $4 = 1 \times 45^{\circ}$ 

Counting direction

1 = cw

2 = ccw

Optional on request

- Ex 2/22 (only for connection types 3 and 4)
- surface protection salt spray tested

Specifications subject to change without notice, 98-0ENC-03-A, released 11/27/2023

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Compact magnetic

ESAV361 / ENAV361 (shaft / hollow shaft)

**Analog** 

Order code Hollow shaft ENAV361. XXXXX.XXX2

If for each parameter of an encoder the **underlined preferred option** is selected, then the delivery time will be 10 working days for a maximum of 10 pieces.

Qts. up to 50 pcs. of these types generally have a delivery time of 15 working days.



a Flange

2 = with stator coupling, IP65, ø 46 mm [1.81"]

3 = with spring element, long, IP65

5 = with stator coupling, IP67, ø 46 mm [1.81"]

6 = with spring element, long, IP67

Blind hollow shaft (insertion depth max. 18.5 mm [0.73"])

1 = Ø 6 mm [0.24"]

3 = Ø 8 mm [0.32"]

4 = ø 10 mm [0.39"]

 $2 = \emptyset 1/4''$ 

© Output circuit 1)

3 = current output

4 = voltage output

Type of connection

1 = axial cable, 1 m [3.28'] PVC

A = axial cable, special length PVC \*)

2 = radial cable, 1 m [3.28'] PVC

B = radial cable, special length PVC \*)

3 = axial M12 connector, 5-pin

4 = radial M12 connector, 5-pin

\*) Available special lengths (connection types A, B): 2, 3, 5, 8, 10, 15 m [5.56, 9.84, 16.40, 26.25, 32.80, 49.21'] order code expansion .XXXX = length in dm Ex.: 8.M3671A.243A.3112.0030 (for cable length 3 m)

• Interface / resolution / supply voltage

3 = 4 ... 20 mA / 12 bit / 10 ... 30 V DC

4 = 0 ... 10 V / 12 bit / 15 ... 30 V DC

5 = 0 ... 5 V / 11 bit / 10 ... 30 V DC

Measuring range

 $1 = 1 \times 360^{\circ}$ 

2 = 1 x 180°

 $3 = 1 \times 90^{\circ}$ 

 $4 = 1 \times 45^{\circ}$ 

Counting direction

1 = cw

2 = ccw

Optional on request

- Ex 2/22 (only for connection types 3 and 4)

- surface protection salt spray tested

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<sup>1)</sup> Output circuit "3" only in conjunction with interface "3", output circuit "4" only in conjunction with interface "4" or "5".



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Mechanical characteristics

**Analog** 

### Technical data

Flactrical characte	ristics current	interface 4 20 mA		
Electrical characteristics current i				
Supply voltage		10 30 V DC		
Current consumption (	no load)	max. 30 mA		
Reverse polarity protection of the supply voltage		yes		
Short-circuit proof out	puts	yes 1)		
Measuring range		45°, 90°, 180° or 360°		
DA converter resolution	n	12 bit		
Angular measurement	deviation <sup>2)</sup>	±0,5°		
Temperature coefficien	nt	< 100 ppm/K		
Repeat accuracy, at 25°C [77°F]		±0.2°		
Output load	at 10 V DC at 24 V DC at 30 V DC	max. 200 Ohm max. 900 Ohm max. 1200 Ohm		
Setting time		< 1 ms, R <sub>Burden</sub> = 900 Ohm, 25°C [77°F]		
LEDs (green/red)		- system status - current loop interruption — input load too high - reference point display (only with factory settings) at cw: betw. 0° and 1° at ccw: betw. 0° and -1°		
SET input		level = +V for 1 s minimum		
PowerON Time		< 1 s		
Update rate		1 ms		

Electrical characte	ristics voltage	interface 0 10 V / 0 5 V		
Supply voltage	output 0 5 V	10 30 V DC		
	output 0 10 V	15 30 V DC		
Current consumption (	no load)	max. 30 mA		
Reverse polarity protes supply voltage	ction of the	yes		
Short-circuit proof out	puts	yes 1)		
Measuring range		45°, 90°, 180° or 360°		
DA converter resolution				
	0 5 V	11 bit		
Angular measurement	deviation <sup>2)</sup>	±0,5°		
Temperature coefficien	nt	< 100 ppm/K		
Repeat accuracy, at 25	°C [77°F]	±0.2°		
Current output		max. 10 mA		
Setting time		$< 1 \text{ ms, R}_{Load} = 1000 \text{ Ohm, } 25^{\circ}\text{C } [77^{\circ}\text{F}]$		
LEDs (green/red)		<ul> <li>system status</li> <li>reference point display (only with factory settings) at cw: betw. 0° and 1° at ccw: betw. 0° and -1°</li> </ul>		
SET input		level = +V for 1 s minimum		
PowerON Time		<1s		
Update rate		1 ms		

Maximum speed shaft or blind hollow shaft version without shaft seal (IP65)	6000 min <sup>-1</sup> 3000 min <sup>-1</sup> (continuous)	
shaft or blind hollow shaft version with shaft seal (IP67)	4000 min <sup>-1</sup> 2000 min <sup>-1</sup> (continuous)	
Starting torque at 20 °C [68 °F] without shaft sea with shaft seal (IP67	< 0.007 Nm < 0.01 Nm	
Shaft load capacity radia axia	** **	
Weight	approx. 210 g [7.41 oz]	
Weight Protection acc. to EN 60529	approx. 210 g [7.41 oz] IP65 or IP67	
•		
Protection acc. to EN 60529	IP65 or IP67 -40 °C +85 °C [-40 °F +185 °F] stainless steel aluminum zinc die-cast	
Protection acc. to EN 60529  Working temperature range  Materials shaft / hollow shaft flange housing	IP65 or IP67 -40 °C +85 °C [-40 °F +185 °F] stainless steel aluminum zinc die-cast PVC	

SET input		
Input		active HIGH
Input type		comparator
Signal level (+V = supply voltage)	HIGH LOW	min. 60 % of +V, max: +V max. 30 % of +V
Input current		< 0.5 mA
Min. pulse duration (SET)		10 ms
Input delay		1 ms
New position data readable after	•	1 ms
Internal processing time		200 ms

The encoder can be set to zero at any position by means of a HIGH signal on the SET input. Other preset values can be factory-programmed. The SET input has a signal processing time of approx. 1 ms, after which the new position data can be read. Once the SET function has been triggered, the encoder requires an internal processing time of typ. 200 ms; during this time the supply voltage must not be switched off.

The SET function should be carried out whilst the encoder is at rest.

The number of preset value writing cycles is limited to 10,000.

If this input is not used, it should be connected to 0 V (Encoder ground GND) in order to avoid interferences.

Approvals			
E1 compliant in accordance with	ECE guideline		
UL compliant in accordance with	File no. E224618		
CE compliant in accordance with			
EMC Directive	2014/30/EU		
RoHS Directive	2011/65/EU		
ATEX Directive	2014/34/EU (for Ex 2/22 variants)		
UKCA compliant in accordance with			
EMC Regulations	S.I. 2016/1091		
RoHS Regulations	S.I. 2012/3032		
UKEX Regulations	S.I. 2016/1107 (for Ex 2/22 variants)		

<sup>1)</sup> When the supply voltage is correctly applied.

But not output to +V. Supply voltage and sensor output signal are not galvanically isolated.

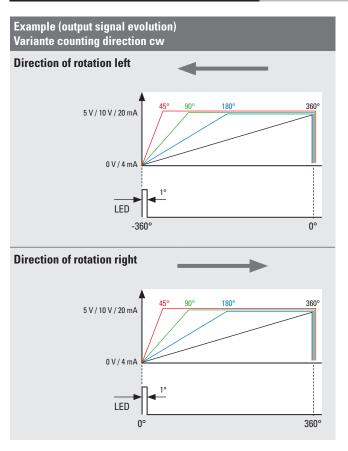
<sup>2)</sup> Over the whole temperature range.

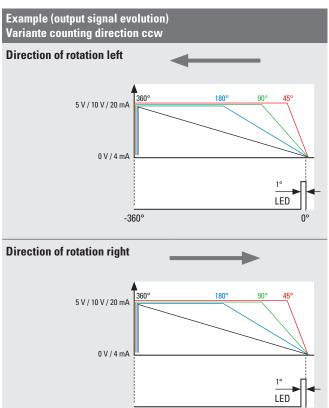


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### ESAV361 / ENAV361 (shaft / hollow shaft)

**Analog** 





#### **Terminal assignment**

Interface	Type of connection	Cable (isolate unused cores individually before initial start-up)					
3	3 1240	Signal:	0 V	+V	+I	SET	
(current)	1, 2, A, B	Core color:	WH	BN	GN	GY	
Interface	Type of connection	M12 connector, 5 pin					
3	3, 4	Signal:	0 V	+V	+1	SET	-
(current)		Pin:	3	2	1	5	4
Interface	Type of connection	Cable (isolate unused cores individually before initial start-up)					
4, 5	1, 2, A, B	Signal:	0 V	+V	+U	SET	
(voltage)	1, 2, A, D	Core color:	WH	BN	GN	GY	
Interface	Type of connection	M12 connector, 5 pin					
4, 5	4, 5	Signal:	0 V	+V	+U	SET	_
(voltage)	3, 4	Pin:	3	2	1	5	4

Top view of mating side, male contact base



M12 connector, 5-pin

+V: Supply voltage encoder +V DC

0 V: Supply voltage encoder ground GND (0 V)

+U: Voltage +I: Current SET: Set input



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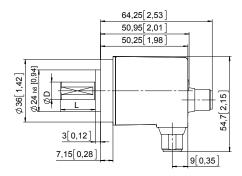
**Analog** 

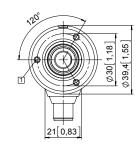
### **Dimensions shaft version**

Dimensions in mm [inch]

#### Clamping flange, ø 36 [1.42] Flange type 1 and 3

1 3 x M3, 6 [0.24] deep



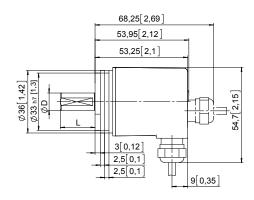


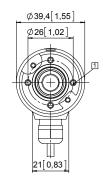
D	Fit	L
6 [0.24]	h7	12.5 [0.49]
8 [0.32]	h7	15 [0.59]
10 [0.39]	f7	20 [0.79]
1/4"	h7	12.5 [0.49]

#### Synchro flange, ø 36 [1.42] Flange type 2 and 4

1 4 x M3, 6 [0.24] deep

D	Fit	L
6 [0.24]	h7	12.5 [0.49]
8 [0.32]	h7	15 [0.59]
10 [0.39]	f7	20 [0.79]
1/4"	h7	12.5 [0.49]







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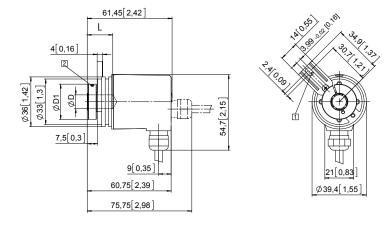
#### **Dimensions hollow shaft version**

Dimensions in mm [inch]

## Flange with spring element, long Flange type 3 and 6

- Slot spring element, recommendation: cylindrical pin DIN 7, ø 4 [0.16]
- 2 Recommended torque for the clamping ring 0.7 Nm

D	Fit	L	D1		
6 [0.24]	H7	18.5 [0.73]	24 [0.94]		
8 [0.32]	H7	18.5 [0.73]	25.5 [1.00]		
10 [0.39]	H7	18.5 [0.73]	25.5 [1.00]		
1/4" H7 18.5 [0.73] 24 [0.94]					
I = insertion denth max blind hollow shaft					



## Flange with stator coupling, ø 46 [1.81] Flange type 2 and 5

1 Recommended torque for the clamping ring 0.7 Nm

D	Fit	L	D1
6 [0.24]	H7	18.5 [0.73]	24 [0.94]
8 [0.32]	H7	18.5 [0.73]	25.5 [1.00]
10 [0.39]	H7	18.5 [0.73]	25.5 [1.00]
1/4"	H7	18.5 [0.73]	24 [0.94]
L = insertion depth max. blind hollow shaft			

